



英杰明自动化

Egemin Automation

*Automation for competitive advantage*

自动化领域的竞争优势

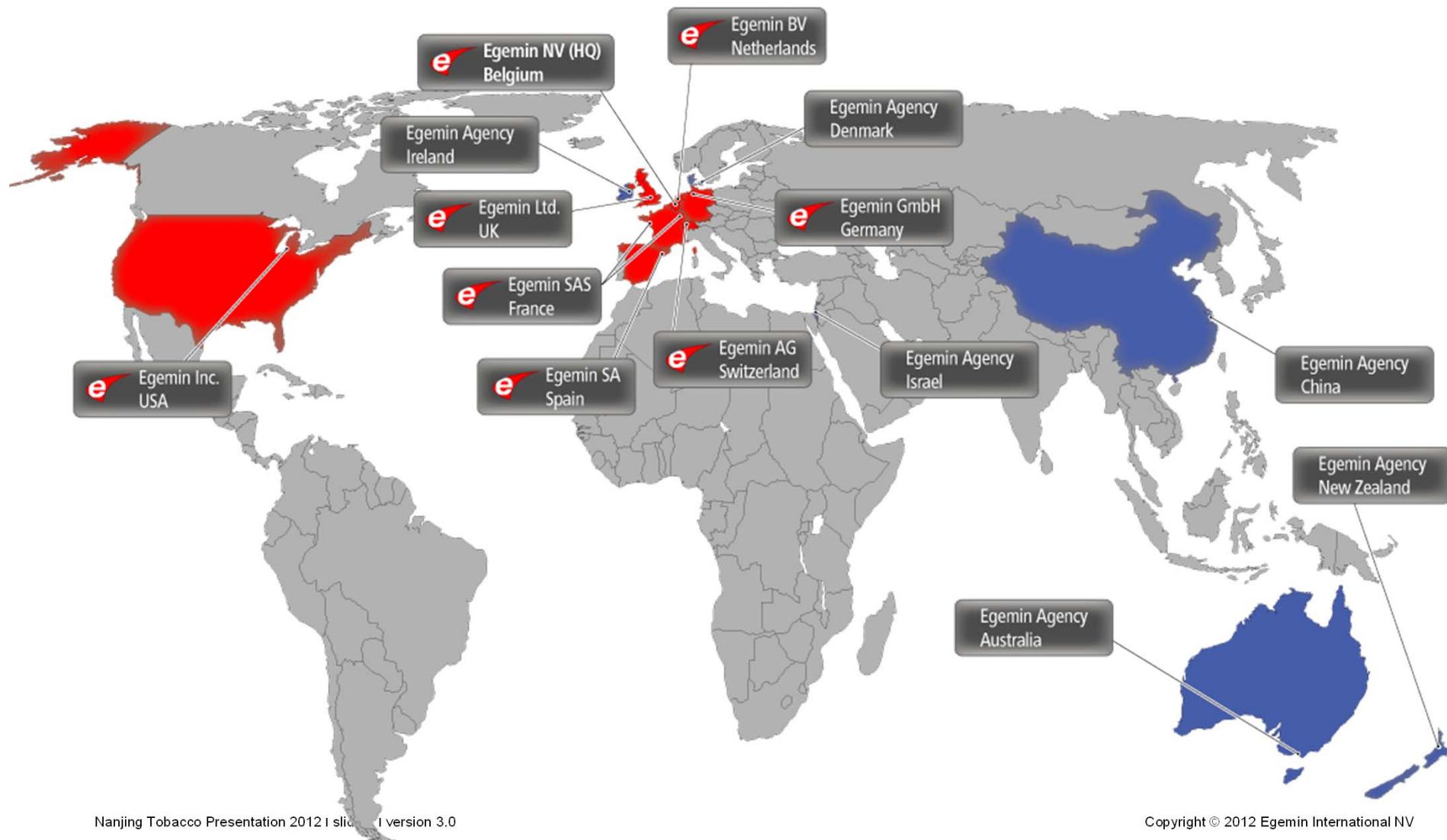
# 智能化自动导引小车 *AGV The Human Way*

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VP International

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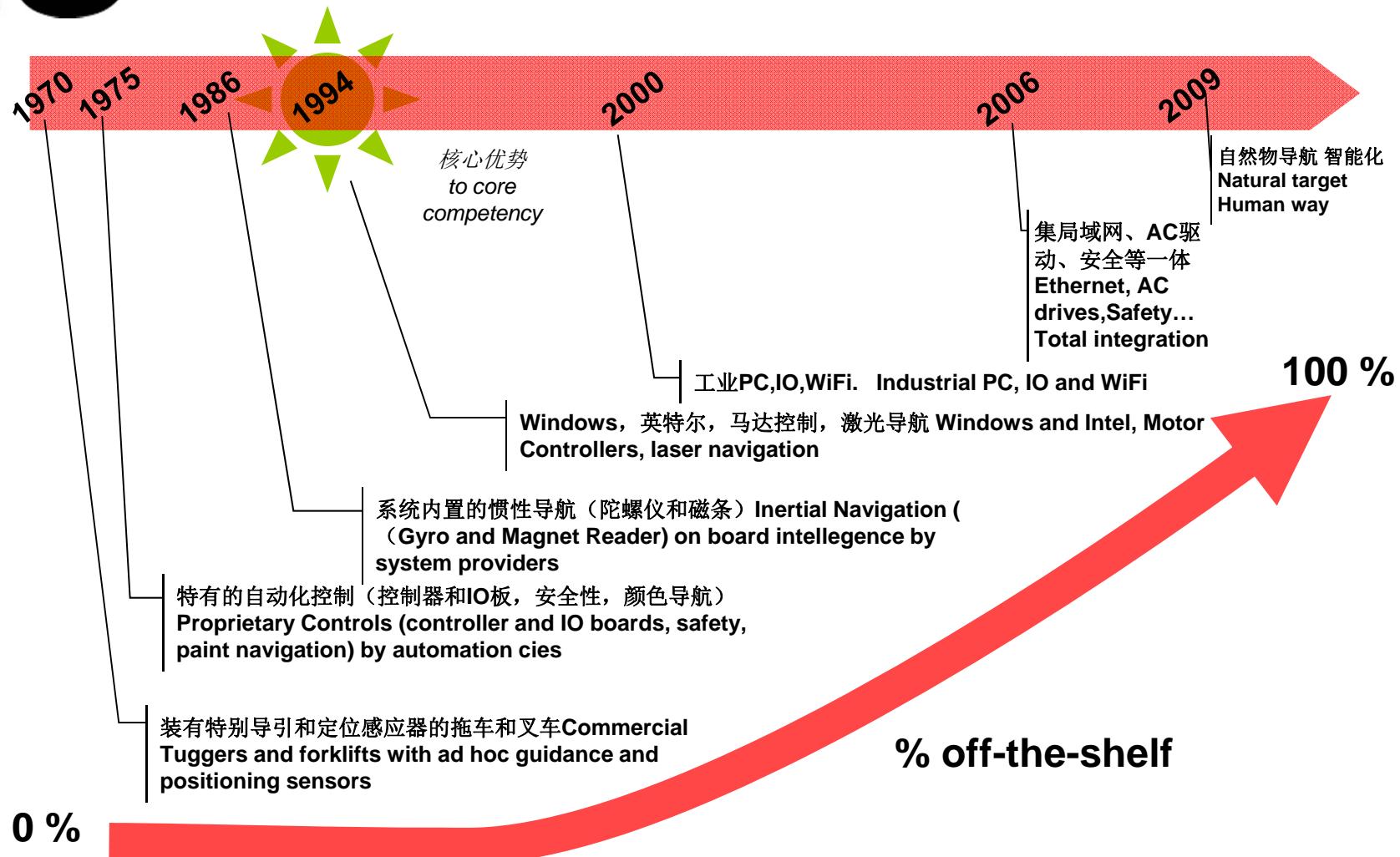
**egemin**  
HANDLING AUTOMATION

## 英杰明分布 *Egemin world wide Presence*



## ***EGEMIN AGV Market Position 英杰明AGV市场定位***

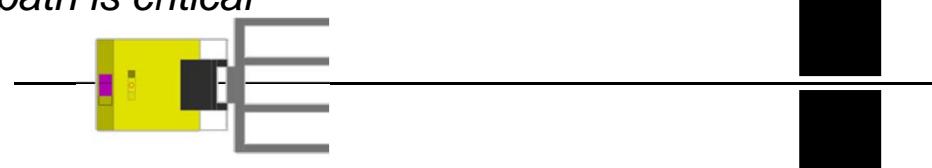
- » 1968年开始自动导引小车的生产AGV business since 1968
- » 行业内最早从事自动导引车研究，并不断发展  
**Oldest in the Market, going strong**
- » 第一家将IPC集成到AGV的公司  
**First one to integrate IPC on board of AGV**
- » 第一家100%OTS的公司**First one to have 100% OTS equipment**
- » 第一家使用OTS货物搬运的公司**First one to use OTS load handling**
- » 第一家拥有多种导航方式的公司**First one to have multimode navigation**
- » 第一家使用自然物导航方式的公司**First one to have natural targeting**
- » 目标—智能化自动导引车 **Towards...the Human way EGV approach**



## 智能化The Human Way

### AGV小车功能回顾 *Historical AGV functionality*

- AGV小车沿着设定路线准确运行 AGVs follow fixed paths at a high degree of accuracy
- 载货和小车运行路线有着至关重要的联系 Load positioning relative to the path is critical



### 焦点 *Issues*

- AGV与AGV机械部件的不同 AGV to AGV mechanical differences
- AGV与AGV运行轨迹的不同 AGV to AGV tracking differences
- 货物定位的不准确性 Load positioning inaccuracies
- 允许误差 Build-up of tolerances
- 多个单一功能的传感器 Multiple single-function sensors

## 智能化The Human Way

### 新的方式—智能化 A new approach – the Human Way

- 基于环境 Based on the environment
- 货物位置判断 Assess the location of the load
- 尽可能的驶近货物 Drive up to the load as closely as possible
- 自我调整适应货物高度 Adjust the mechanism to match the load position

### 要求This requires

- 动态调整AVG小车运行路线 the AGV to adjust the path dynamically
- 小车根据货物特征自动调整高度 the AGV mechanism to compensate for load alignment

### 不适用范围 Non-application specific

- 单一的点对点运送 Single-load point-to-point applications
- 深度仓库存储 Deep-lane stacking warehouse storage
- 货车自动装卸 Automatic truck loading and automatic truck unloading

# 智能化 *The Human Way*

## 总结 *Overview*

- 根据客户需求使用合适的导航传感器 *All navigation capable sensors are used when required*
- 单一导航系统保证小车在机器, 拖车, 工厂/仓库和深度堆放巷道内的精确导航 *Single navigation system ensures accurate guidance between machines, trailer, factory/warehouse floor and deep lane storage*
- 充分利用环境里的现有因素 进行导航 *The environment is used in addition to known navigation elements (targets, magnets...)*
- 智能AGV小车可以根据环境(货物位置, 卡车停放处)自动选择路线 *Intelligent AGVs alter the guide path to compensate for the environment (load location, truck location...)*

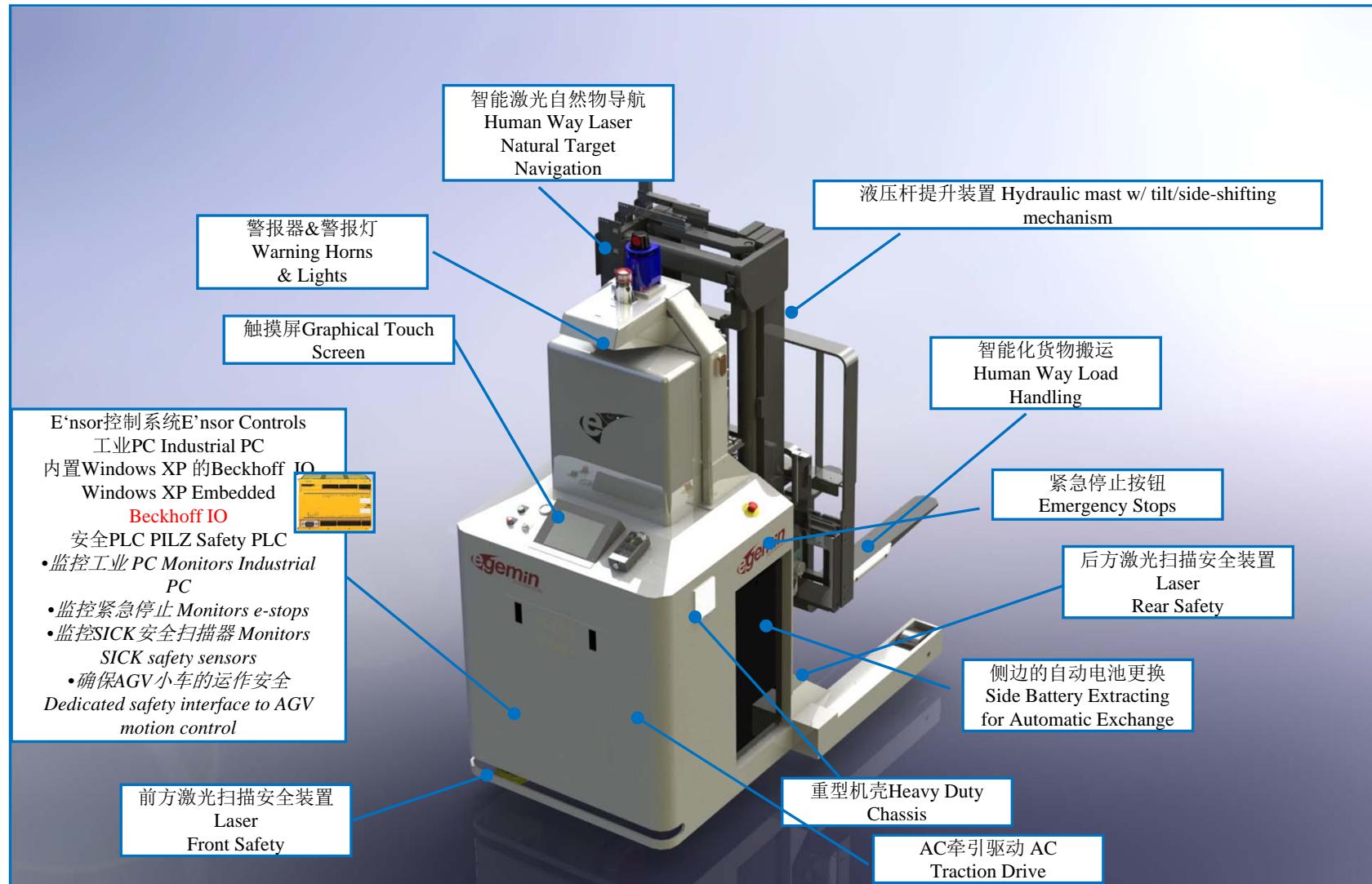
# AGV智能化 AGV The Human Way

一个控制方案 One Controls Solution



所有合适的导航传感器都被不停使用 All navigation capable sensors are continuously used

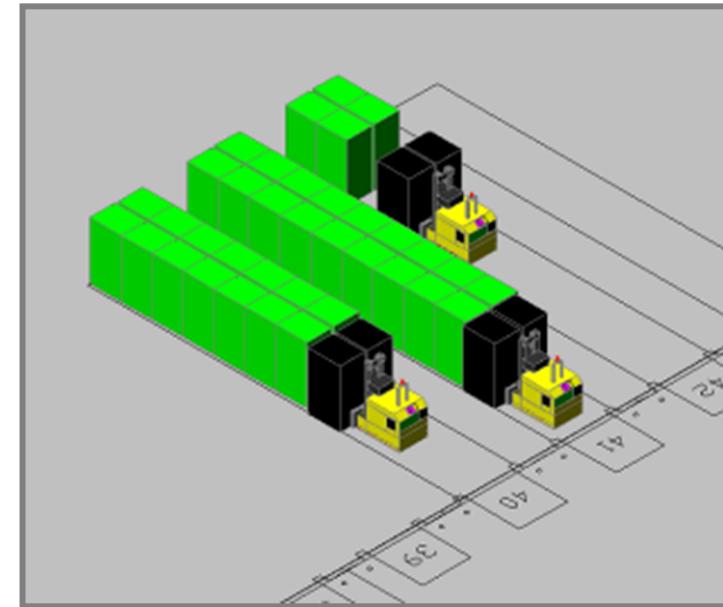
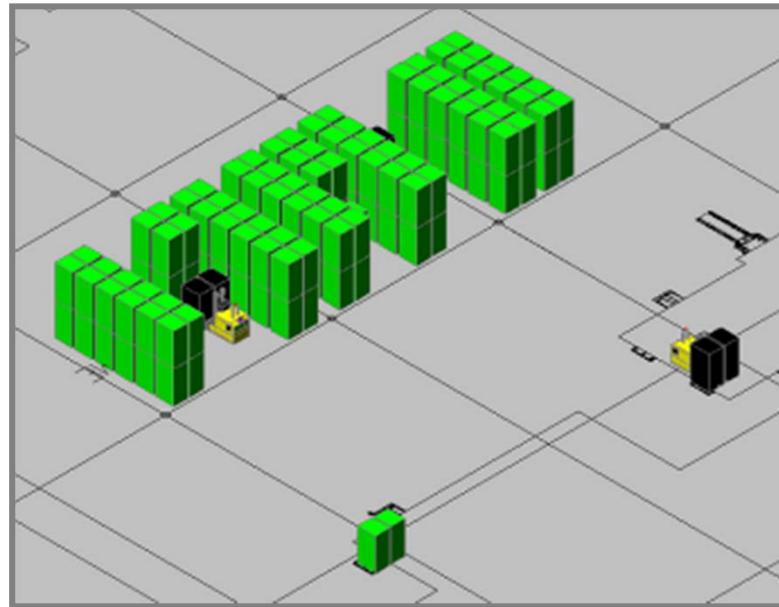
# 智能化 AGV The Human Way



# 智能化AGV *The Human Way*

## *One For All*

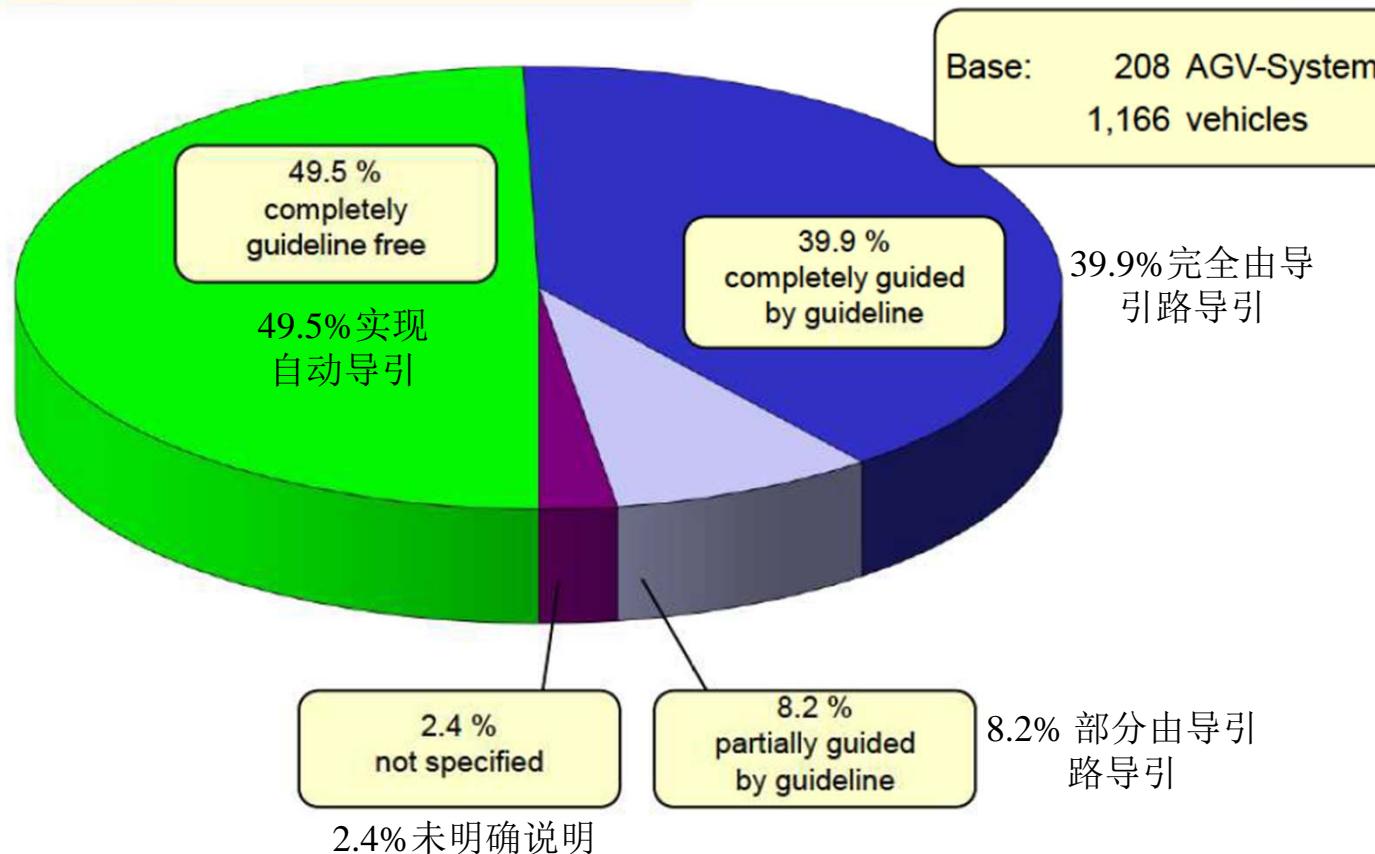
单一的导航系统确保小车在拖车，工厂/仓库地面和深层堆垛区域之间的准确运行 *Single navigation system ensures accurate guidance between trailer, factory/warehouse floor and deep lane storage*



## 智能化AGV *The Human way*

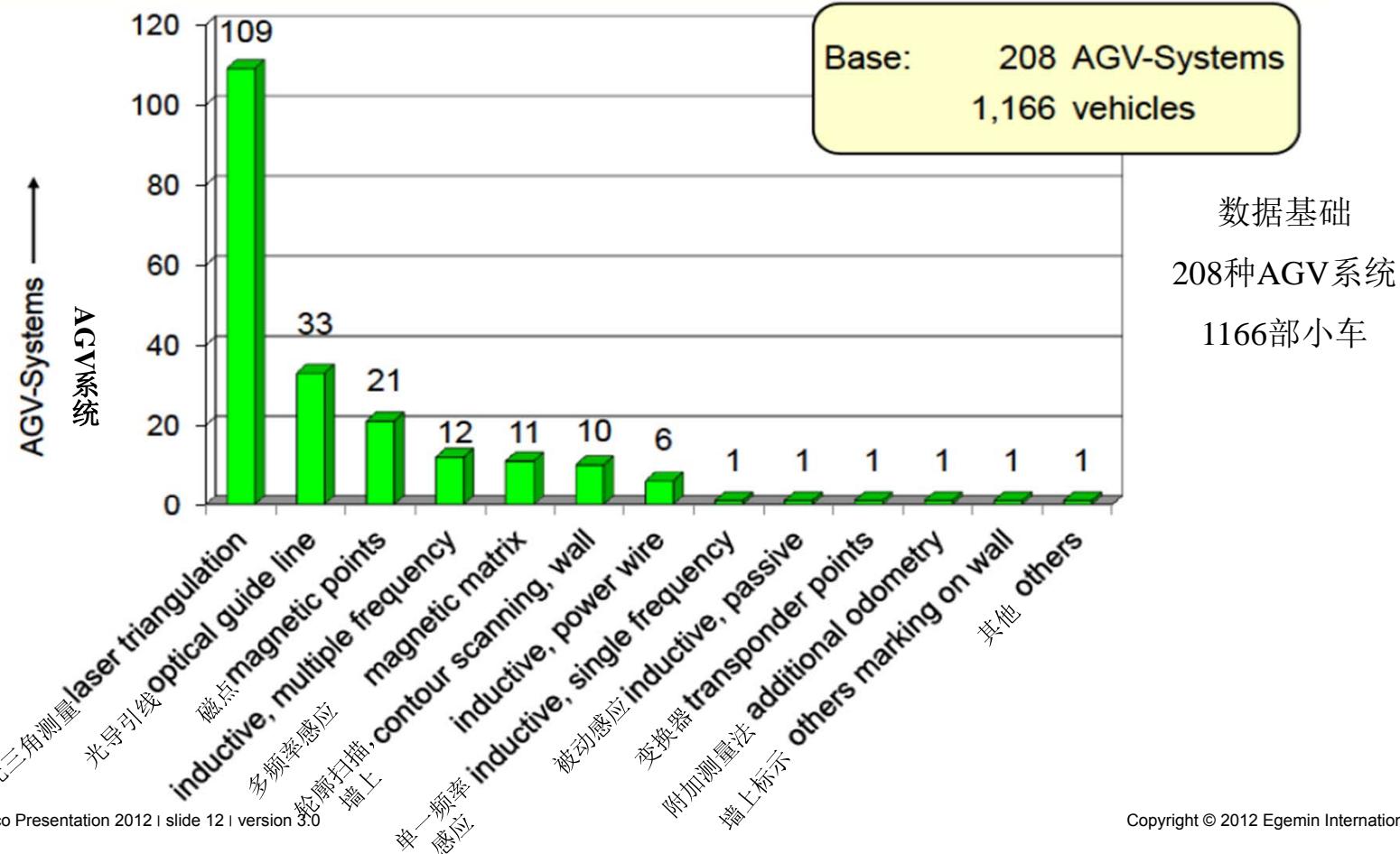
Guiding system in new AGV-Systems,  
opening 2011 2011年开发的新的AGV导航系统

**PSLT**  
Leibniz Universität  
Hannover



# 智能化 AGV *The Human Way*

Guiding technique in new AGV-Systems,  
opening 2011 2011年开发的新的AGV系统导航技术



# 智能化The Human Way

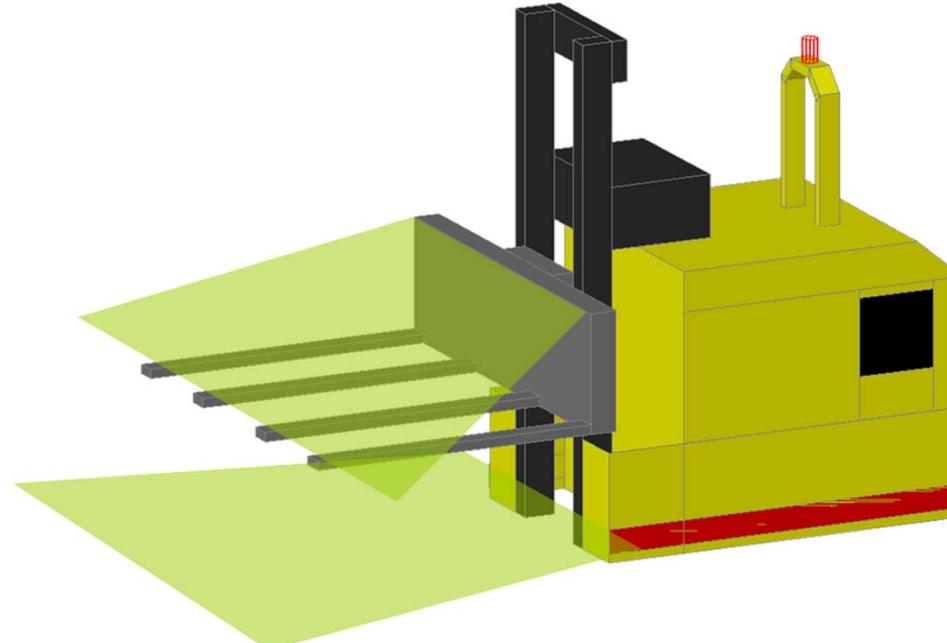
多种夹抱方式 Multi-Plane Positive-Feedback

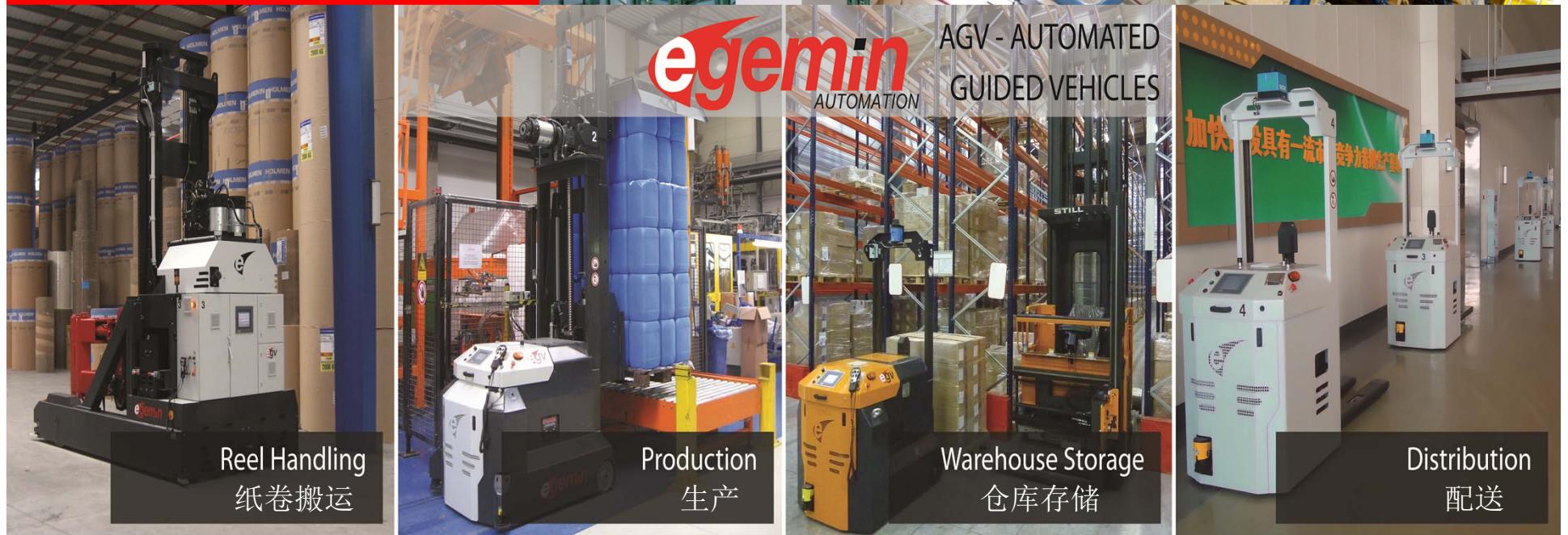


## 智能化 AGV *The Human Way*

### 多种夹抱方式 *Multi-Plane Positive-Feedback*

- 上货卸货时的主动测量 *Actively measures on-board and off-board loads*
- 反馈的信息让小车可以根据货物进行动态调节 *Feedback provides information for mechanism to dynamically adjust to load*





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Thank you for the Attention  
谢谢观赏

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